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theory.the book answers key questions about fuzzy systems and. a course in fuzzy systems and control. 1 in the last decade or so, fuzzy logic (fl) has evolved into an important component of many control systems and engineering applications.. solutions to problems. control 3 0 0 3 cl 662 fuzzy logic and neural networks 3 0 0 3. biology solutions. in this paper, we present a fuzzy logic control (flc) model of a continuous stirred tank reactor (cstr) for the purpose of quick and accurate estimation of the parameters of the flc. the estimation of the parameters by the proposed flc model is based on the fuzzy logic framework. the proposed model can be used to study the performance of the cstr as well as to predict the behavior of the cstr. thus, it is beneficial for the industrial applications, which are related to industrial chemicals such as oil refineries, petrochemical plants, and pharmaceutical plants, and for research applications such

as the predictive modeling of the kinetics of the reaction in the cstr. the numerical results indicate the effectiveness of the proposed flc model for the cstr.

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in this paper, we present a fuzzy controller for the problem of mobile robot path tracking for a cedra rescue robot. after designing the fuzzy tracking controller, the membership functions will be optimized by evolutionary algorithms in order to obtain more acceptable results. previous article in issue next article in issue keywords trajectory tracking mobile robot differential evolution genetic algorithm fuzzy membership functions recommended articles citing articles (0) hossein nejat pishkenari was born in 1981. he received his b.s., m. and ph.d. degrees in mechanical engineering from sharif university of technology in 2003, 2005 and

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